Random Processes

Monte Carlo Simulation

Random or Stochastic processes

You cannot predict from the observation of one event, how the next will come out

Examples:

Coin: the only prediction about outcome – 50% the coin will land on its tail

Dice: In large number of throws – probability 1/6

Question: What is the most probable number for the sum of two dice?

	1	2	3	4	5	6
1	2	3	4	5	6	7
2	3	4	5	6	7	8
3	4	5	6	7	8	9
4	5	6	7	8	9	10
5	6	7	8	9	10	11
6	7	8	9	10	11	12

36 possibilities

6 times – for **7**

Applications for MC simulation

- Stochastic processes

- Complex systems (science)

- Numerical integration

- Risk management

- Financial planning

- Cryptography

- …

How do we do that?

- You let the computer to throw "the coin" and record the outcome

- You need a program that generates randomly a variable
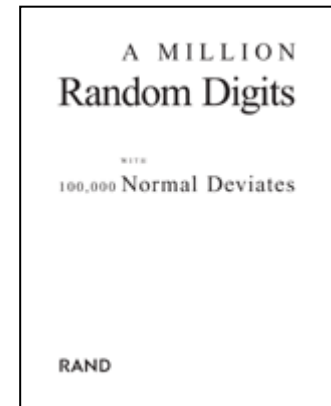 … with relevant probability distribution

Part 1

Random number generators

Sources of Random Numbers

- Tables

- Hardware (external sources of random numbers – generates random numbers from a physics process.

- Software (source of pseudorandom numbers)

Tables

Most significant

A Million Random Digits with 100,000 Normal Deviates

by RAND

```
00000    10097 32533    76520 13586    34673 54876    80959 09117    39292 74945
00001    37542 04805    64894 74296    24805 24037    20636 10402    00822 91665
00002    08422 68953    19645 09303    23209 02560    15953 34764    35080 33606
00003    99019 02529    09376 70715    38311 31165    88676 74397    04436 27659
00004    12807 99970    80157 36147    64032 36653    98951 16877    12171 76833
00005    66065 74717    34072 76850    36697 36170    65813 39885    11199 29170
00006    31060 10805    45571 82406    35303 42614    86799 07439    23403 09732
00007    85269 77602    02051 65692    68665 74818    73053 85247    18623 88579
00008    63573 32135    05325 47048    90553 57548    28468 28709    83491 25624
00009    73796 45753    03529 64778    35808 34282    60935 20344    35273 88435
00010    98520 17767    14905 68607    22109 40558    60970 93433    50500 73998
00011    11805 05431    39808 27732    50725 68248    29405 24201    52775 67851
00012    83452 99634    06288 98083    13746 70078    18475 40610    68711 77817
00013    88685 40200    86507 58401    36766 67951    90364 76493    29609 11062
00014    99594 67348    87517 64969    91826 08928    93785 61368    23478 34113
. . . . .
```

Software - Random Number Generators

- There are no true random number generators but pseudo RNG!

- Reason: computers have only a limited number of bits to represent a number

- It means: the sequence of random numbers will repeat itself (period of the generator)

Good   Random Number Generators

Two important issues:

1. randomness
2. knowledge of the distribution.

Other (still important) issues

1. independent of the previous number
2. long period
3. produce the same sequence if started with same initial conditions
4. fast

Two basic techniques for RNG

The standard methods of generating pseudorandom numbers use modular reduction in congruential relationships.

Two basic techniques for generating uniform random numbers:

1.   congruential methods

2.   feedback shift register methods.

For each basic technique there are many variations.

Linear Congruent Method for RNG

Generates a random sequence of numbers
$\{x_1, x_2, \ldots x_k\}$ of length M over the interval $[0, M-1]$

$$x_i = \mathrm{mod}(ax_{i-1} + c, M) = remainder\left(\frac{ax_{i-1} + c}{M}\right) \quad 0 \leq x_{i-1} < M$$

- starting value x_0 is called "seed"

- coefficients a and c should be chosen very carefully

note:

$$\mathrm{mod}(b, M) = b - \mathrm{int}(b/M) * M$$

the method was suggested by D. H. Lehmer in 1948

Example:

$$x_i = \text{mod}(ax_{i-1} + c, M)$$

$$\text{mod}(b, M) = b - \text{int}(b/M) * M$$

a=4, c=1, M=9, x_1=3

x_2 = 4

x_3 = 8

x_4 = 6

x_{5-10} = 7, 2, 0, 1, 5, 3

interval: 0-8, i.e. [0,M-1]

period: 9   i.e. M numbers (then repeat)

Random Numbers on interval [A,B]

■ Scale results from x_i on [0,M-1] to y_i on [0,1]

$$y_i = x_i /(M - 1)$$

■ Scale results from x_i on [0,1] to y_i on [A,B]

$$y_i = A + (B - A)x_i$$

Magic numbers for Linear Congruent Method

- M (length of the sequence) is quite large

- However there is no overflow
  (for 32 bit machines $M=2^{31} \approx 2*10^9$)

- Good "magic" number for linear congruent method:

$$x_i = \mathrm{mod}(ax_{i-1} + c, M)$$

a = 16,807, c = 0, M = 2,147,483,647

for c = 0 "multiplicative congruential generator":

Other Linear Congruential Generators

✓ Multiple Recursive Generators
many versions including "Lagged Fibonacci"

✓ Matrix Congruential Generators

✓ Add-with-Carry, Subtract-with-Borrow, and Multiply - with-Carry Generators

Other Generators

✓ Nonlinear Congruential Generators

✓ Feedback Shift Register Generators

✓ Generators Based on Cellular Automata

✓ Generators Based on Chaotic Systems

✓ …

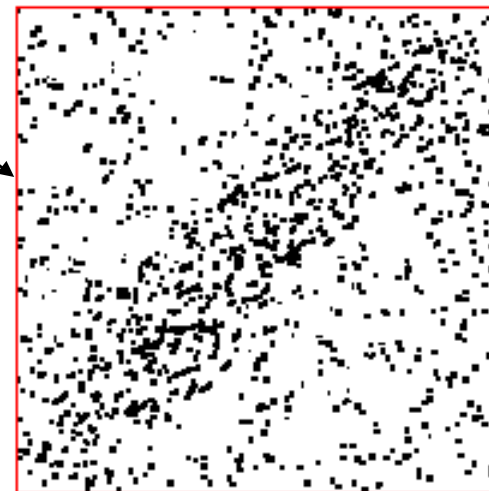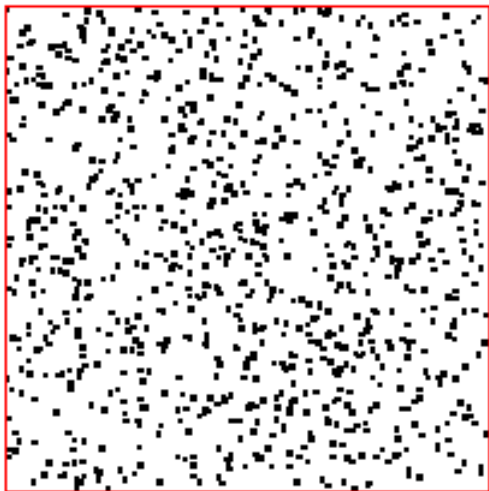James E. Gentle – "Random Number Generation and Monte Carlo Methods

Second edition - 2004

How can we check the RNG?

Plots:

- 2D figure, where x_i and y_i are from two random sequences (parking lot test)

- 3D figure (x_i, y_i, z_i)

- 2D figure for correlation (x_i, x_{i+k})

How can we check the RNG?

Example of other assessments

Uniformity. A random number sequence should contain numbers distributed in the unit interval with equal probability. Use bins.

k-th momentum
$$\left\langle x^k \right\rangle = \frac{1}{N} \sum_{i=1}^{N} x_i^k \approx \frac{1}{k+1}$$

near-neighbor correlation
$$\frac{1}{N} \sum_{i=1}^{N} x_i x_{i+k} \approx \frac{1}{4}$$

Software for RNG

C/C++ and Fortran (90,95) provide built-in uniform random number generators,

but … except for small studies, these built-in generators should be avoided.

A number of Fortran and C/C++ programs are available in

StatLib: http://lib.stat.cmu.edu/

NetLib: http://www.netlib.org/liblist.html

GAMS: http://gams.nist.gov/

GNU Scientific Library (GSL) http://www.gnu.org/software/gsl/

IMSL (International Mathematics and Statistics Library) libraries contain a large number of RNGs

"Industrial" methods in C/C++ and Fortran

- rand
- random
- drand48
- rn
- drand
- srand
- …

1. call SEED

   Changes the starting point of the pseudorandom number generator.

2. call RANDOM

   Returns a pseudorandom number greater than or equal to zero and less than one from the uniform distribution.

Standard RNG in C++

#include <cstdlib>   library

srand(*seed*)   is used to initialize the RNG

rand()   returns a pseudo random integer in the range 0 to RAND_MAX. RAND_MAX = 32767

Generating integer random numbers in a range i1 – i2:

random_i = i1 + (rand()%(i2-i1+1));

a better method to do the same

random_i = i1 + int(1.0*(i2-i1+1)*rand()/(RAND_MAX+1.0));

Generating real random numbers between 0.0 and 1.0

drandom = 1.0*rand()/(RAND_MAX+1);

Example: srand and rand in C++

```cpp
// generate integer random numbers between i1 and i2
#include <iostream>
#include <cstdlib>
#include <cmath>
#include <ctime>
using namespace std;

int main ()
{
  int nmax=10;              /* generate 10 random numbers*/
  int i1=1, i2=6, irandom;
  srand (123);             /* initial seed */
//srand(time(NULL)); // better to "randomize" seed values

  for (int i=0; i < nmax; i=i+1)
  {
   irandom = i1+rand()%(i2-i1+1);/* number between i1 & i2*/
   cout << " " << irandom << endl;
  }
  system("pause");
  return 0;
}
```

```
3
4
6
1
6
2
6
3
5
3
```
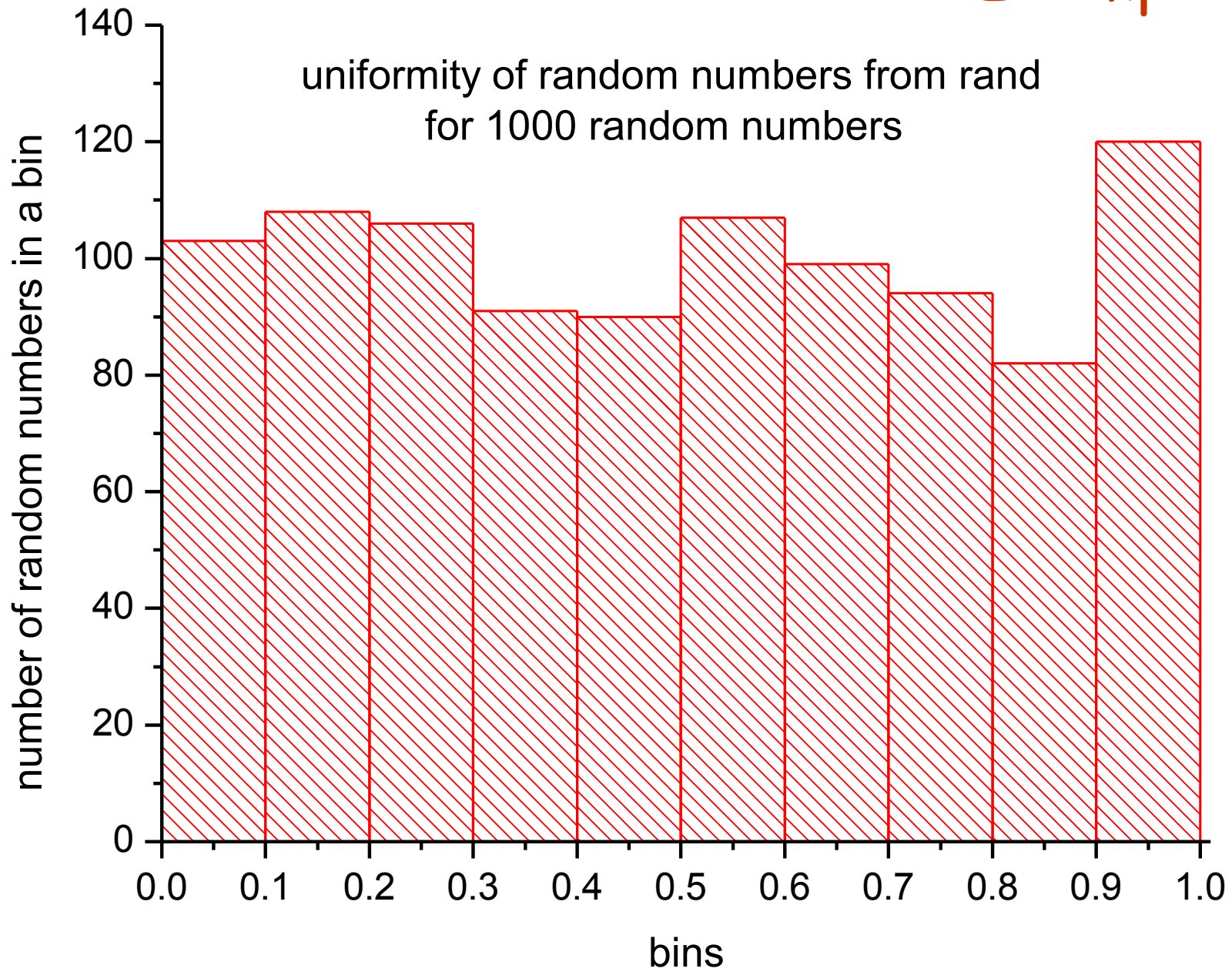
Example: cont. for float

```cpp
/* generate random numbers between 0.0 and 1.0 */
#include <iostream>
#include <iomanip>
#include <cstdlib>
#include <cmath>
#include <ctime>
using namespace std;
int main ()
{
  int nmax = 10;     /*generate 10 random number*/
  double drandom;
  cout.precision(4);
  cout.setf(ios::fixed | ios::showpoint);

  srand(4567); /* initial seed value */
  for (int i=0; i < nmax; i=i+1)
  {
      drandom = 1.0*rand()/(RAND_MAX+1);
      cout << "d = " << drandom << endl;
  }
  system("pause");
  return 0;
}
```
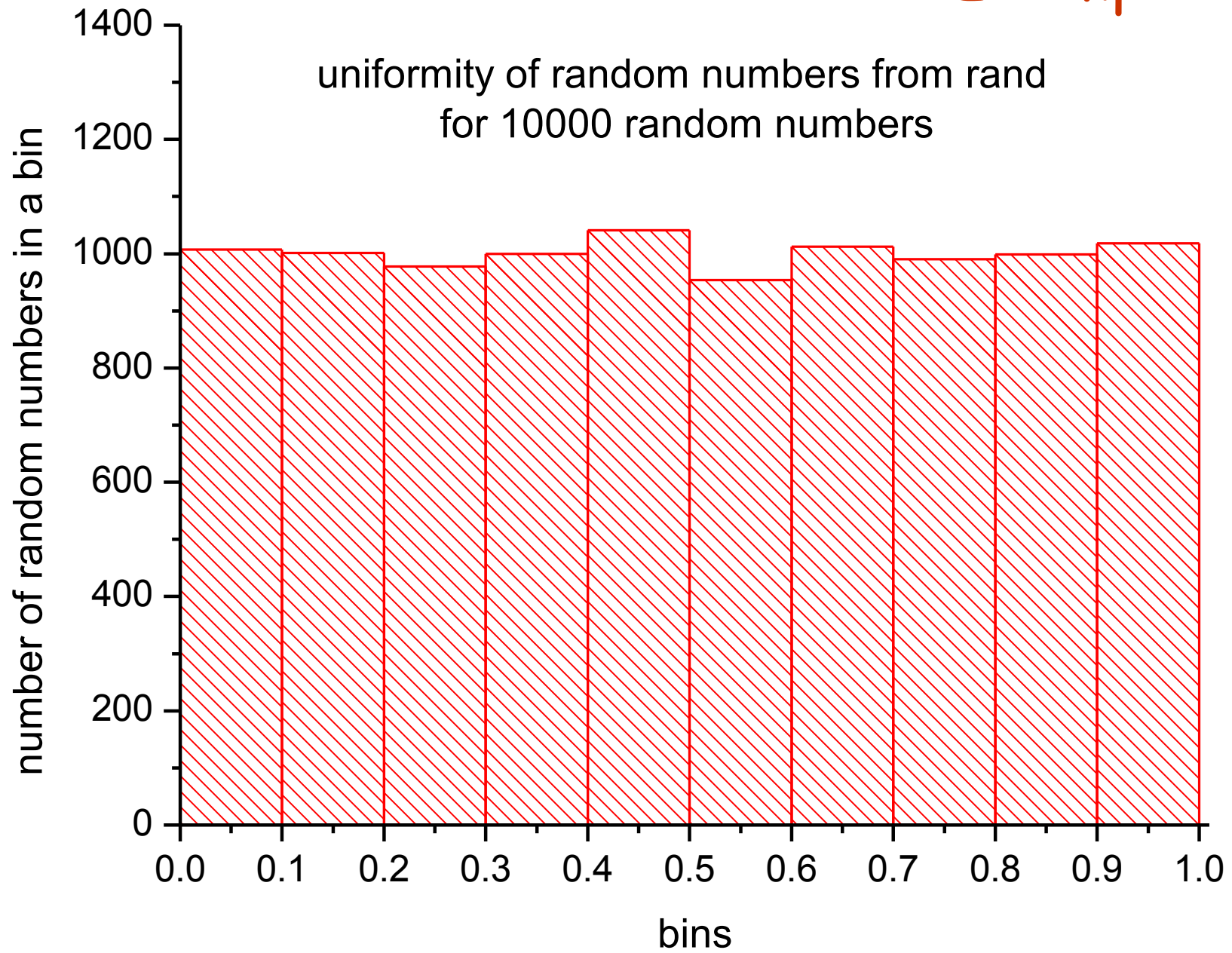
0.4563
0.2816
0.4452
0.8693
0.8514
0.6432
0.0493
0.9999
0.6017
0.0548

Example
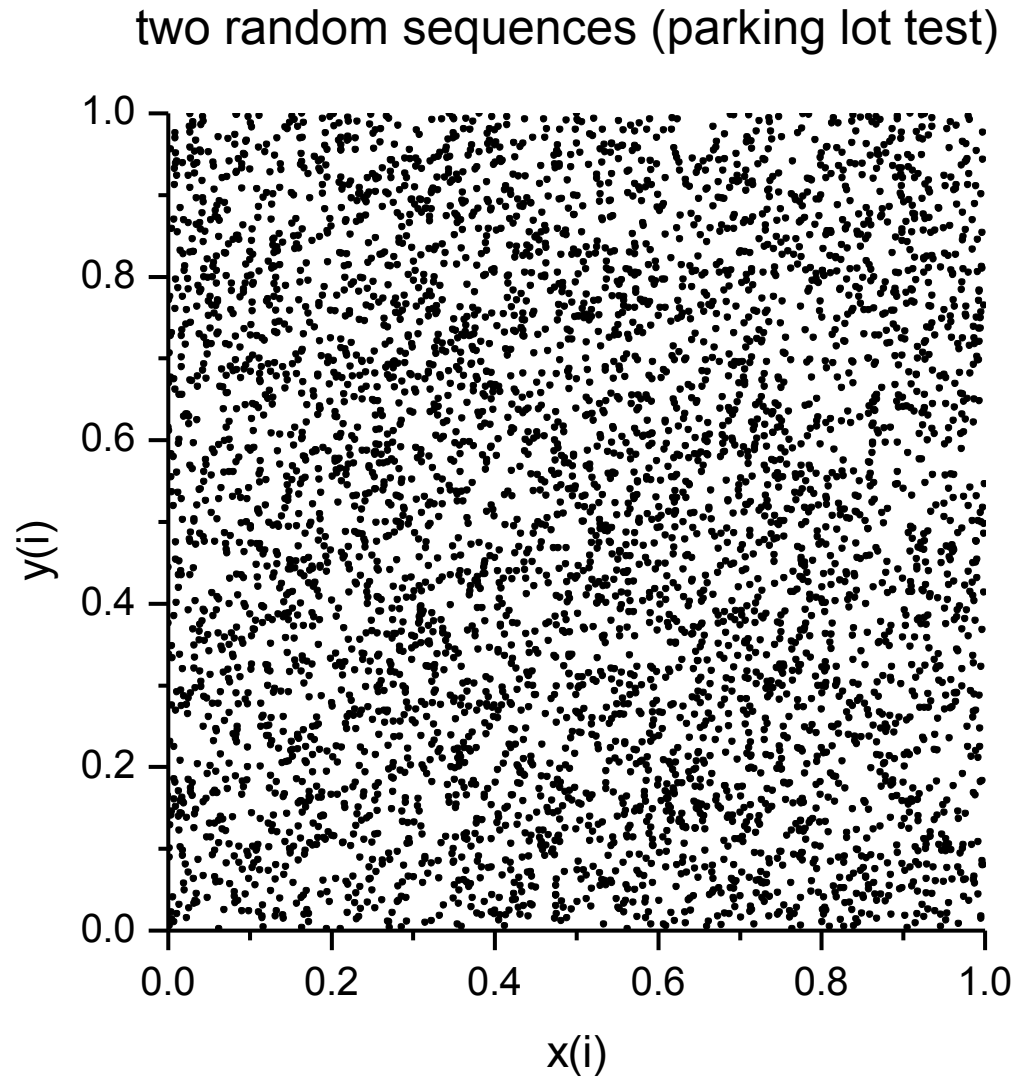
uniformity of random numbers from rand
for 10000 random numbers

Example:

2D distribution for two random sequences x_i and y_i

k-th moment of the random number distribution

two random sequences (parking lot test)
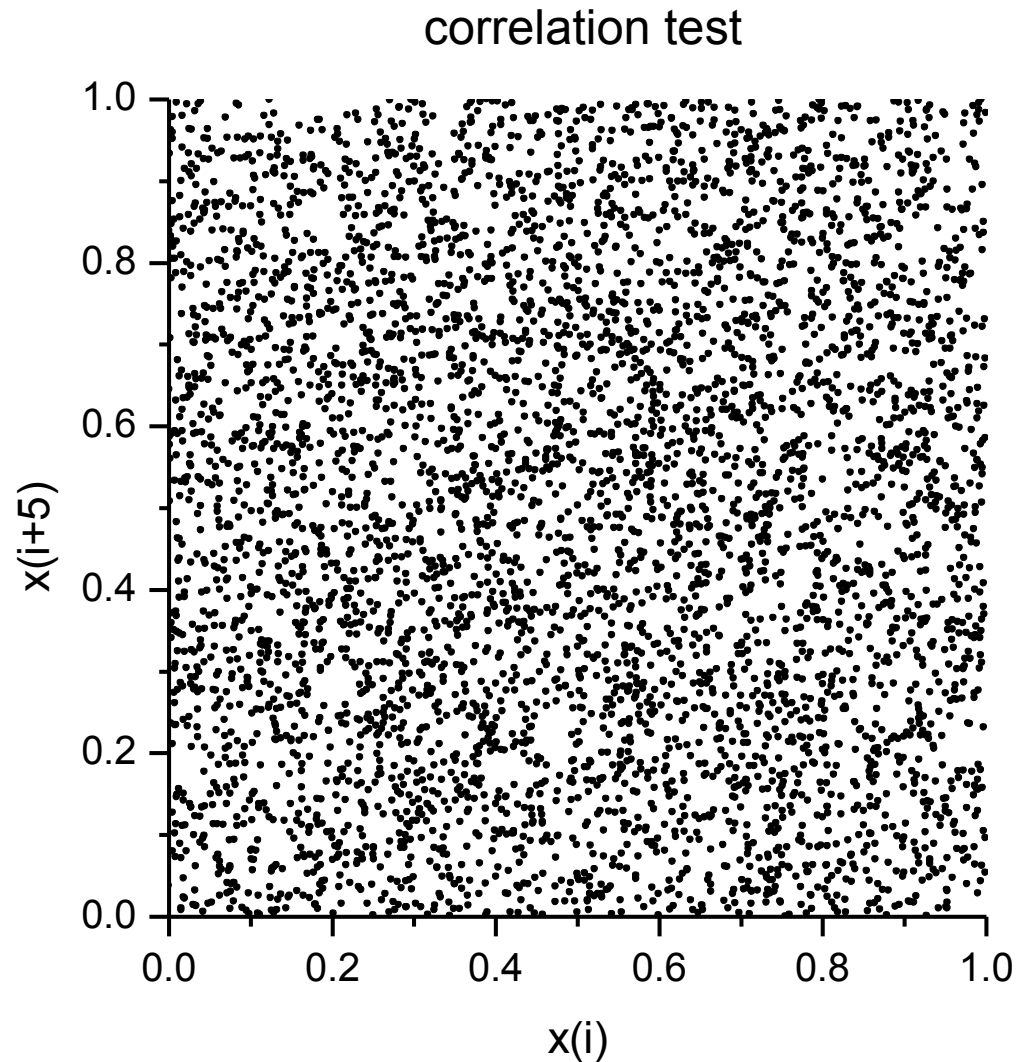

5000 points,
k-th momentum $<x^4>=0.1991$
near-neighbor correlation = 0.2507

Example:

2D distribution for
correlation (x_i, x_{i+5})

correlation test

5000 points,
k-th momentum $\langle x^4 \rangle = 0.1991$
near-neighbor correlation = 0.2507

Comment to rand in C++

"The version of rand() that comes with your C++ compiler will in all probability be a pretty simple generator and wouldn't be appropriate for scientific use. … It may well be random enough for use in simple programs and games."

Jacobs, B. C++ Random Numbers. A tutorial for beginners, introducing the functions srand() and rand()

see also http://www.netlib.org/random/

Source codes for various random number generators in C and Fortran, including the RANLIB library

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Practice 1 (homework)

1. Write a program to generate random numbers using the linear congruent method

2. Plot 2D distribution for two random sequences x_i and y_i

3. Plot 2D distribution for correlation (x_i, x_{i+4})

4. Evaluate 5-th moment of the random number distribution

5. Use some built-in RNG for problems 2-4.

Part 2

Monte Carlo Integration

Monte Carlo Integration

- There are very many methods for numerical integration

- Can MC approach compete with sophisticated methods?

- Can we gain anything from integration by "gambling"?

Problem: High-Dimensional Integration

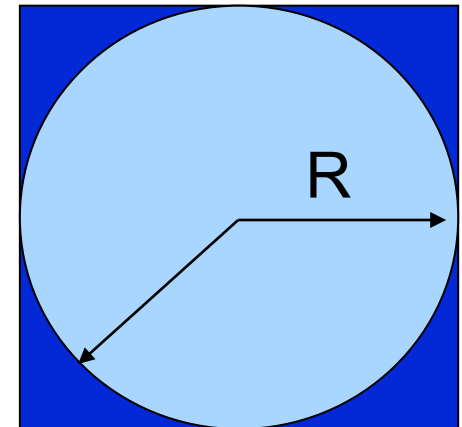Example: Integration for a system with 12 electrons.

- ■ 3*12=36 dimensional integral

- ■ If 64 points for each integration then =64^{36} points to evaluate

- ■ For 1 Tera Flop computer = 10^{53} seconds

- ■ That is … 3 times more then the age of the universe!

Integration by rejection
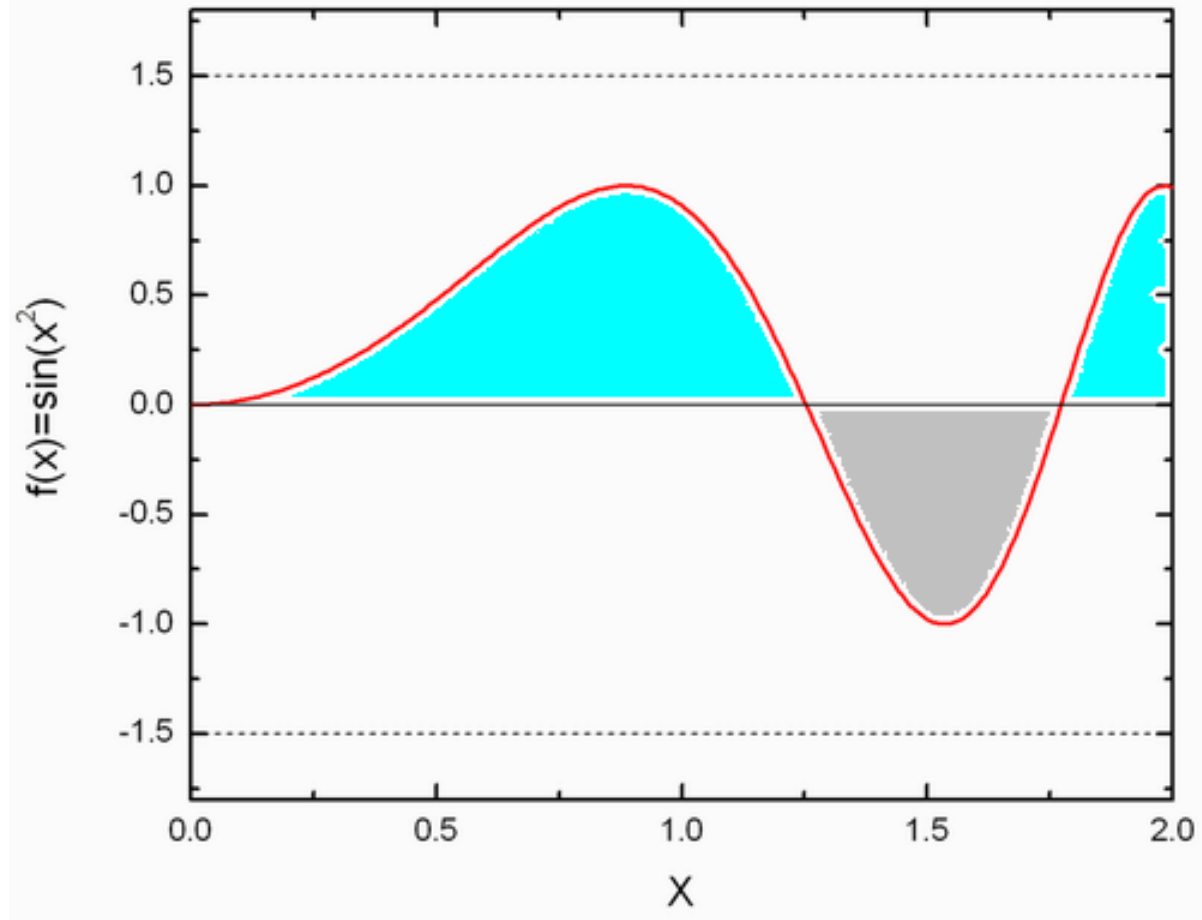# hit and miss method

Example: area of a circle

Radius: R

Area of the square: $4R^2$

1. loop over N

2. generate a pair of random numbers x and y on [-1,1]

3. if (x*x+y*y) < 1 then m=m+1

4. since A_{circle}/A_{square} = m/N

5. A_{circle} = m/N*A_{square} = (m/N)*$4R^2$

One more example

Compute N pairs of random numbers x_i and y_i with $0.0 \leq x \leq 2.0$ and $-1.5 \leq y \leq 1.5$.

$$F_n = A\left(\frac{n_+ - n_-}{N}\right)$$

Integration by mean value

$$I = \int_a^b f(x)dx = (b-a)\langle f \rangle$$

$$I = \int_a^b f(x)dx \approx (b-a)\frac{1}{N}\sum_{i=1}^{N} f(x_i) \pm \Delta S$$

$$\Delta S = (b-a)\sqrt{\frac{\langle f^2 \rangle - \langle f \rangle^2}{N}}$$

$$\langle f \rangle = \frac{1}{N}\sum_{i=1}^{N} f(x_i) \qquad \langle f^2 \rangle = \frac{1}{N}\sum_{i=1}^{N} f^2(x_i)$$

the error evaluation is based on the normal distribution

Traditional methods (midpoint, Simpson, …) – N points are chosen with equal spacing.

Monte Carlo method – random sampling

Midpoint vs Monte Carlo method error

Consider a one-dimensional integral: $\int_{x_l}^{x_h} f(x)\,dx$. We can evaluate this integral numerically by dividing the interval x_l to x_h into N identical subdivisions of width

$$h = \frac{x_h - x_l}{N}.$$

Let x_i be the midpoint of the ith subdivision, and let $f_i = f(x_i)$. Our approximation to the integral takes the form

$$\int_{x_l}^{x_h} f(x)\,dx \simeq \sum_{i=1}^{N} f_i\, h$$

This "midpoint method" is not particularly accurate, but is very easy to generalize to multi-dimensional integrals.
What is the error associated with the midpoint method?
The error is the product of the error per subdivision, which is $O(h^2)$, and the number of subdivisions, which is $O(h^{-1})$. The error per subdivision follows from the linear variation of $f(x)$ within each subdivision. Thus, the overall error is $O(h^2) \times O(h^{-1}) = O(h)$. Since, $h \propto N^{-1}$, we can write

$$\int_{x_l}^{x_h} f(x)\,dx \simeq \sum_{i=1}^{N} f_i\, h + O(N^{-1}).$$

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Error in midpoint m-d for 2-dim integral

Let us now consider a two-dimensional integral. For instance, the area enclosed by a curve. We can evaluate such an integral by dividing space into identical squares of dimension h, and then counting the number of squares, N (say), whose midpoints lie within the curve. Our approximation to the integral then takes the form

$$A \simeq N h^2.$$

This is the two-dimensional generalization of the midpoint method. What is the error associated with the midpoint method in two-dimensions? The error is generated by those squares which are intersected by the curve. These squares either contribute wholly or not at all to the integral, depending on whether their midpoints lie within the curve. In reality, only those parts of the intersected squares which lie within the curve should contribute to the integral The error is the product of the area of a given square, which is $O(h^2)$, and the number of squares intersected by the curve, which is $O(h^{-1})$
$\Rightarrow$ the overall error is $O(h^2) \times O(h^{-1}) = O(h) = O(N^{-1/2})$.

$$\Rightarrow \quad A = N h^2 + O(N^{-1/2}).$$

Error in midpoint m-d for 3-dim integral

Let us now consider a three-dimensional integral represented by the volume enclosed by a surface. We can evaluate such an integral by dividing space into identical cubes of dimension h, and then counting the number of cubes, N (say), whose midpoints lie within the surface. Our approximation to the integral then takes the form

$$V \simeq N h^3.$$

This is the three-dimensional generalization of the midpoint method.

What is the error associated with the midpoint method in three-dimensions? The error is generated by those cubes which are intersected by the surface. These cubes either contribute wholly or not at all to the integral, depending on whether their midpoints lie within the surface. In reality, only those parts of the intersected cubes which lie within the surface should contribute to the integral. The error is the product of the volume of a given cube, which is $O(h^3)$, and the number of cubes intersected by the surface, which is $O(h^{-2})$
$\Rightarrow$ the overall error is $O(h^3) \times O(h^{-2}) = O(h) = O(N^{-1/3})$.

$$\Rightarrow \quad V = N h^3 + O(N^{-1/3}).$$

Error in midpoint m-d for d-dim integral

Finally, consider using the midpoint method to evaluate the volume, V, of a d-dimensional hypervolume enclosed by a $(d-1)$-dimensional hypersurface. It is clear, from the above examples, that
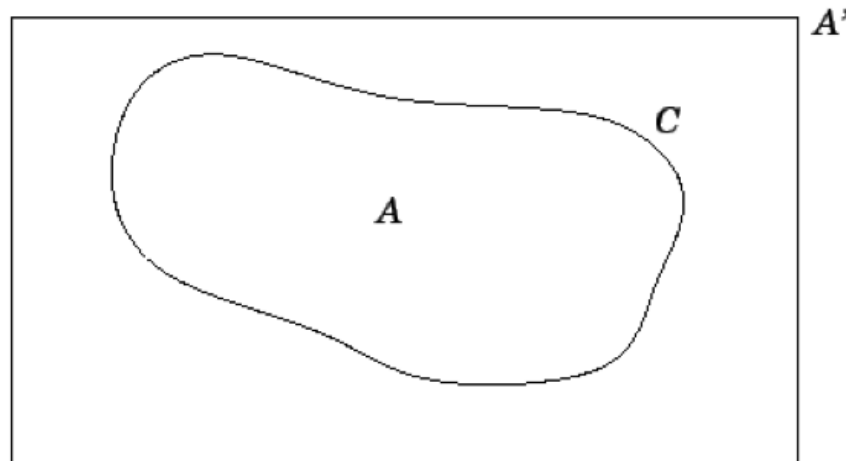
$$V = N\,h^d + O(N^{-1/d}),$$

 where N is the number of identical hypercubes into which the hypervolume is divided. Note the increasingly slow fall-off of the error with N as the dimensionality, d, becomes greater. The explanation for this phenomenon is quite simple. Suppose that $N = 10^6$. With $N = 10^6$ we can divide a unit line into (identical) subdivisions whose linear extent is 10^{-6}, but we can only divide a unit area into subdivisions whose linear extent is 10^{-3}, and a unit volume into subdivisions whose linear extent is 10^{-2}. Thus, for a fixed number of subdivisions the grid spacing (and, hence, the integration error) increases dramatically with increasing dimension.

Error in Monte Carlo method

Let us now consider the Monte-Carlo method for evaluating multi-dimensional integrals. Consider, for example, the evaluation of the area, A, enclosed by a curve, C. Suppose that the curve lies wholly within some simple domain of area A', as illustrated below. Let us generate N' points which are randomly distributed throughout A'. Suppose that N of these points lie within curve C. Our estimate for the area enclosed by the curve is simply

$$A = \frac{N}{N'} A'. \qquad (*)$$

What is the error associated with the Monte-Carlo integration method? Well, each point has a probability $p = A/A'$ of lying within the curve. Hence, the determination of whether a given point lies within the curve is like the measurement of a random variable x which has two possible values: 1 (corresponding to the point being inside the curve) with probability p, and 0 (corresponding to the point being outside the curve) with probability $1 - p$. If we make N' measurements of x (i.e., if we scatter N' points throughout A') then the number of points lying within the curve is

$$N = \sum_{i=1,N'} x_i,$$

where x_i denotes the ith measurement of x. Now, the mean value of N is

$$\bar{N} = \sum_{i=1,N'} \bar{x} = N' \bar{x},$$

where

$$\bar{x} = 1 \times p + 0 \times (1 - p) = p.$$

Hence,

$$\bar{N} = N' p = N' \frac{A}{A'},$$

which is consistent with Eq. ($*$). We conclude that, on average, a measurement of N leads to the correct answer.

But, what is the scatter in such a measurement? Well, if σ represents the standard deviation of N then we have

$$\sigma^2 = \overline{(N - \bar{N})^2},$$

which can also be written

$$\sigma^2 = \sum_{i,j,=1,N'} \overline{(x_i - \bar{x})(x_j - \bar{x})}.$$

However, $\overline{(x_i - \bar{x})(x_j - \bar{x})}$ equals $\overline{(x - \bar{x})^2}$ if $i = j$, and equals zero, otherwise, since successive measurements of x are uncorrelated. Hence,

$$\sigma^2 = N' \overline{(x - \bar{x})^2}.$$

Now,

$$\overline{(x - \bar{x})^2} = \overline{(x^2 - 2x\bar{x} + \bar{x}^2)} = \overline{x^2} - \bar{x}^2,$$

and

$$\overline{x^2} = 1^2 \times p + 0^2 \times (1 - p) = p.$$

Error in the MC method

Thus,

$$\overline{(x - \bar{x})^2} = p - p^2 = p\,(1 - p),$$

giving

$$\sigma = \sqrt{N' p\,(1 - p)}.$$

Finally, since the likely values of N lie in the range $N = \bar{N} \pm \sigma$, we can write

$$N = N' \frac{A}{A'} \pm \sqrt{N' \frac{A}{A'}\left(1 - \frac{A}{A'}\right)}.$$

It follows from Eq. $(*)$ that

$$A = A' \frac{N}{N'} \pm \frac{\sqrt{A\,(A' - A)}}{\sqrt{N'}} \qquad (**).$$

$\Rightarrow$ the error scales like $(N')^{-1/2}$.

Error in the MC method in d dimensions

The Monte-Carlo method generalizes immediately to d-dimensions. For instance, consider a d-dimensional hypervolume V enclosed by a $(d-1)$-dimensional hypersurface A. Suppose that A lies wholly within some simple hypervolume V'. We can generate N' points randomly distributed throughout V'. Let N be the number of these points which lie within A. It follows that our estimate for V is simply

$$V = \frac{N}{N'}\, V'.$$

Now, there is nothing in our derivation of Eq. ($**$) which depends on the fact that the integral in question is two-dimensional $\Rightarrow$ we can generalize this equation to give

$$V = V'\, \frac{N}{N'} \pm \frac{\sqrt{V\,(V'-V)}}{\sqrt{N'}}.$$

We conclude that the error associated with Monte-Carlo integration always scales like $(N')^{-1/2}$, irrespective of the dimensionality of the integral.

Comparison of midpoint and MC methods

In the midpoint method, we fill space with an evenly spaced mesh of N (say) points (i.e., the midpoints of the subdivisions), and the overall error scales like $N^{-1/d}$, where d is the dimensionality of the integral.
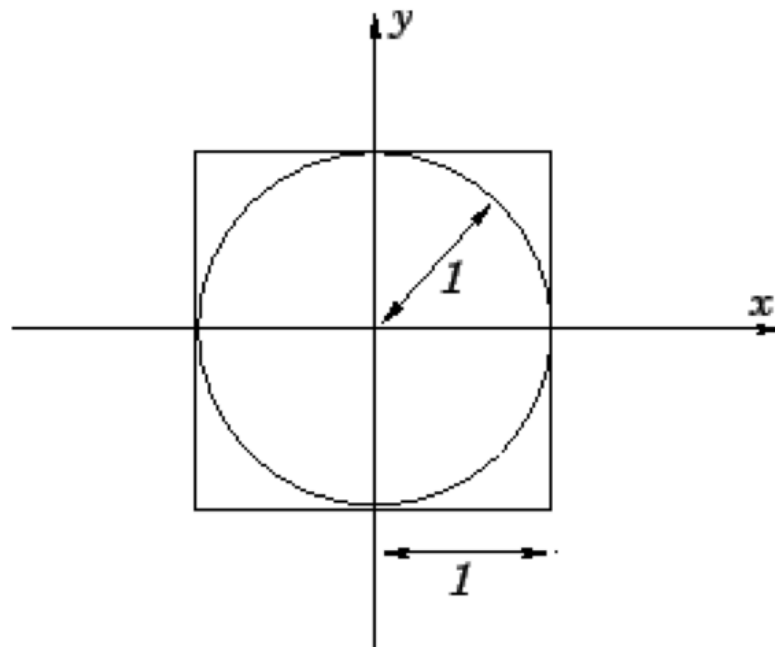
In the Monte-Carlo method, we fill space with N (say) randomly distributed points, and the overall error scales like $N^{-1/2}$, irrespective of the dimensionality of the integral.

For a one-dimensional integral ($d = 1$), the midpoint method is more efficient than the Monte-Carlo method, since in the former case the error scales like N^{-1}, whereas in the latter the error scales like $N^{-1/2}$. For a two-dimensional integral ($d = 2$), the midpoint and Monte-Carlo methods are both equally efficient, since in both cases the error scales like $N^{-1/2}$. Finally, for a three-dimensional integral ($d = 3$), the midpoint method is less efficient than the Monte-Carlo method, since in the former case the error scales like $N^{-1/3}$, whereas in the latter the error scales like $N^{-1/2}$.
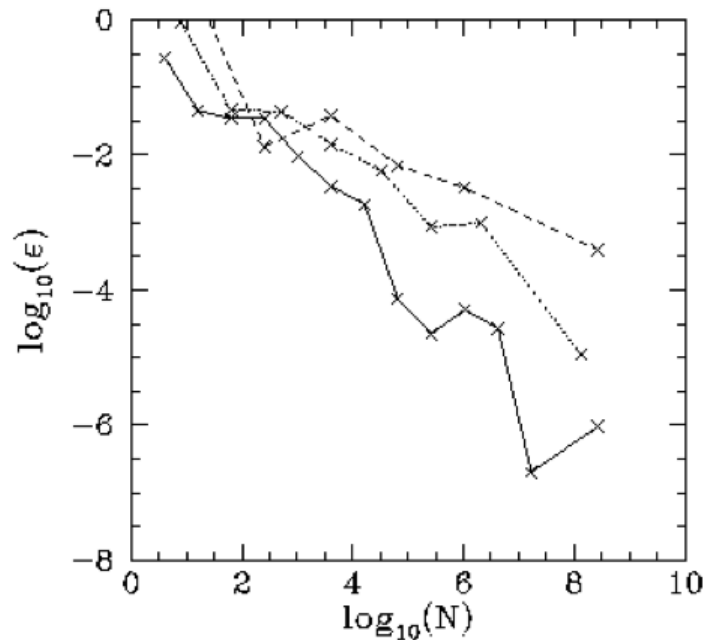
$\Rightarrow$ For a sufficiently high dimension integral the Monte-Carlo method is always going to be more efficient than an integration method (such as the midpoint method) which relies on a uniform grid.
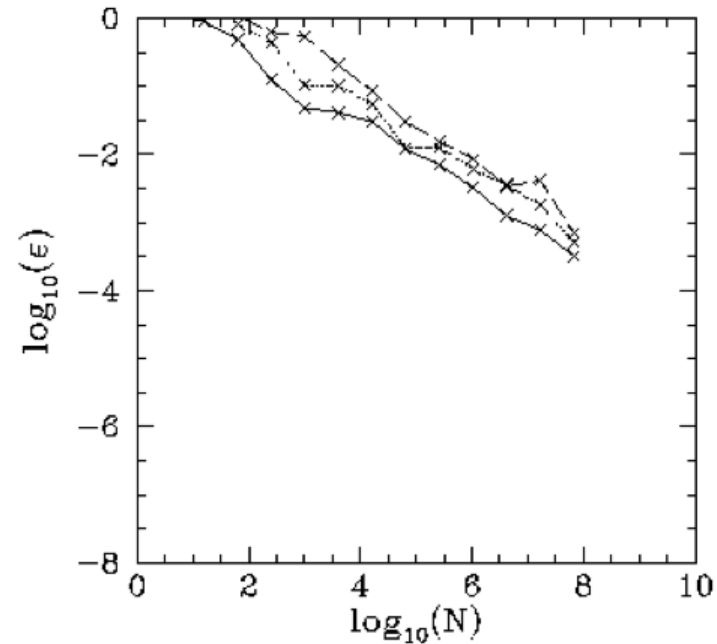
Example: volume of a d-dim sphere

Let us evaluate the volume of a unit-radius d-dimensional sphere, where d runs from 2 to 4, using both the midpoint and Monte-Carlo methods. For both methods, the domain of integration is a cube, centred on the sphere, which is such that the sphere just touches each face of the cube, as illustrated below

The integrals are the area of a unit-radius circle (solid curve), the volume of a unit-radius sphere (dotted curve), and the volume of a unit-radius 4-sphere (dashed curve).

The integration error, ϵ, versus the number of grid-points, N, for three integrals evaluated using the midpoint method.

The integration error, ϵ, versus the number of points, N, for three integrals evaluated using the Monte-Carlo method.

Up to now, we have only considered how the Monte-Carlo method can be employed to evaluate a rather special class of integrals in which the integrand function can only take the values 0 or 1.

However, the Monte-Carlo method can easily be adapted to evaluate more general integrals.

Suppose that we wish to evaluate $\int f\, dV$, where f is a general function and the domain of integration is of arbitrary dimension. We proceed by randomly scattering N points throughout the integration domain and calculating f at each point. Let x_i denote the ith point. The Monte-Carlo approximation to the integral is simply

$$\int f\, dV = \frac{1}{N} \sum_{i=1,N} f(x_i) + O\left(\frac{1}{\sqrt{N}}\right).$$

Error in MC vs Simpson integration

Error in Monte - Carlo   1D case $\dfrac{1}{\sqrt{N}}$

Error in Monte - Carlo   nD case $\dfrac{1}{\sqrt{N}}$

Error in Simson   1D case $\dfrac{1}{N^4}$

Error in Simson   nD case $\left(\dfrac{1}{N^4}\right)^{1/n}$

at n 7 or 8 the error in Monte Carlo integration is similar to that of conventional scheme

Example: 1D integration (C++)

```cpp
 double int_mc1d(double(*f)(double), double a, double b, int n)
/* 1D intergration using Monte-Carlo method for f(x) on [a,b]
input: f - Function to integrate (supplied by a user)
       a - Lower limit of integration
       b - Upper limit of integration
       n - number random points
output:r - Result of integration
Comments: be sure that following headers are included
     #include <cstdlib>
     #include <ctime>
*/
{
   double r, x, u;
   srand(time(NULL)); /* initial seed value (use system time) */

   r = 0.0;

   for (int i = 1; i <= n; i=i+1)
   {
     u = 1.0*rand()/(RAND_MAX+1); // random between 0.0 and 1.0
       x = a + (b-a)*u;            // random x between a and b
       r = r + f(x);
   }
   r = r*(b-a)/n;
   return r;
}
```

Example $\int_0^\pi \sin(x)\,dx = 2.0$

n	Trapez.	Simpson	Monte Carlo
2	1.570796	2.094395	2.483686
4	1.896119	2.004560	2.570860
8	1.974232	2.000269	2.140117
16	1.993570	2.000017	1.994455
32	1.998393	2.000001	2.005999
64	1.999598	2.000000	2.089970
128	1.999900	2.000000	2.000751
256	1.999975	2.000000	2.065036
512	1.999994	2.000000	2.037365
1024	1.999998	2.000000	1.988752
2048	2.000000	2.000000	1.989458
4096	2.000000	2.000000	1.991806
8192	2.000000	2.000000	2.000583
16384	2.000000	2.000000	1.987582
32768	2.000000	2.000000	1.991398
65536	2.000000	2.000000	1.997360

Example $\int\limits_{0}^{\pi} \dfrac{x}{x^2+1} \cos(10x^2)dx = 0.0003156$

n	Trapez.	Simpson	Monte Carlo
64	0.004360	-0.013151	0.081207
128	0.001183	-0.001110	0.155946
256	0.000526	-0.000311	0.071404
512	0.000368	0.000006	0.002110
1024	0.000329	0.000161	-0.004525
2048	0.000319	0.000238	-0.010671
4096	0.000316	0.000277	0.000671
8192	0.000316	0.000296	-0.009300
16384	0.000316	0.000306	-0.009500
32768	0.000316	0.000311	-0.005308
65536	0.000316	0.000313	-0.000414
131072	0.000316	0.000314	0.001100
262144	0.000316	0.000315	0.001933
524288	0.000316	0.000315	0.000606
1048576	0.000316	0.000315	-0.000369
2097152	0.000316	0.000316	0.000866
4194304	0.000316	0.000316	0.000330

many methods to increase accuracy

Example: antithetic variates – using "mirror points"

$$I = \int_{a}^{b} f(x)dx \approx (b-a)\frac{1}{N}\sum_{i=1}^{N/2}\left(f(x_i) + f(a+(b-x_i))\right)$$

Antithetic variates have negative covariances, thus reducing the variance of the sum

more methods can be found in
James E. Gentle – "Random Number Generation and Monte Carlo Methods

Second edition - 2004

Multidimensional Monte Carlo

$$\int_a^b dx \int_c^d dy f(x,y) \cong (b-a)(d-c)\frac{1}{N}\sum_{i=1}^N f(x_i, y_i)$$

Example: nD integration (C++)

```cpp
double int_mckd(double(*fn)(double[],int),double a[],
        double b[], int n, int m)
/* input is similar to 1D integration*/
{
    double r, x[n], p;
    int i, j;
    srand(time(NULL));/* initial seed value (use system time) */
    r = 0.0;
    p = 1.0;

// step 1: calculate the common factor p
     for (j = 0; j < n; j = j+1) p = p*(b[j]-a[j]);

// step 2: integration
     for (i = 1; i <= m; i=i+1)
     {
//        calculate random x[] points
        for (j = 0; j < n; j = j+1)
        {
            x[j] = a[j] + (b[j]-a[j])*rand()/(RAND_MAX+1);
        }
        r = r + fn(x,n);
    }
    r = r*p/m;
    return r;
}
```
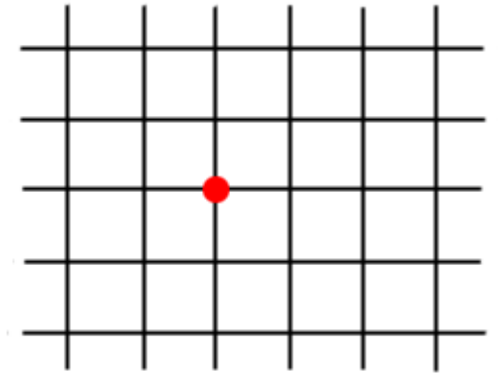
$$\int_0^1 dx_1 \int_0^1 dx_2 \int_0^1 dx_3 \int_0^1 dx_4 \int_0^1 dx_5 \int_0^1 dx_6 \int_0^1 (x_1 + x_2 + \ldots + x_7)^2 dx_7 = 12.83333333$$

Example

	7D Integral
8	11.478669
16	12.632578
32	13.520213
64	13.542921
128	13.263171
256	13.178140
512	12.850561
1024	12.747383
2048	12.745207
4096	12.836080
8192	12.819113
16384	12.790508
32768	12.765735
65536	12.812653
131072	12.809303
262144	12.831216
524288	12.832844

total elapsed time = 1 seconds

Practice: Integration

■ Use Monte Carlo integration (both rejection and mean value methods) to evaluate

$$\int_0^3 \exp(-x)\,dx \quad \text{and} \quad \int_0^5 \sin(2x^2)\,dx$$

■ Evaluate 7-D integral

$$\int_0^1 dx_1 \int_0^1 dx_2 \int_0^1 dx_3 \int_0^1 dx_4 \int_0^1 dx_5 \int_0^1 dx_6 \int_0^1 (x_1 + x_2 + \ldots + x_7)^2\,dx_7$$
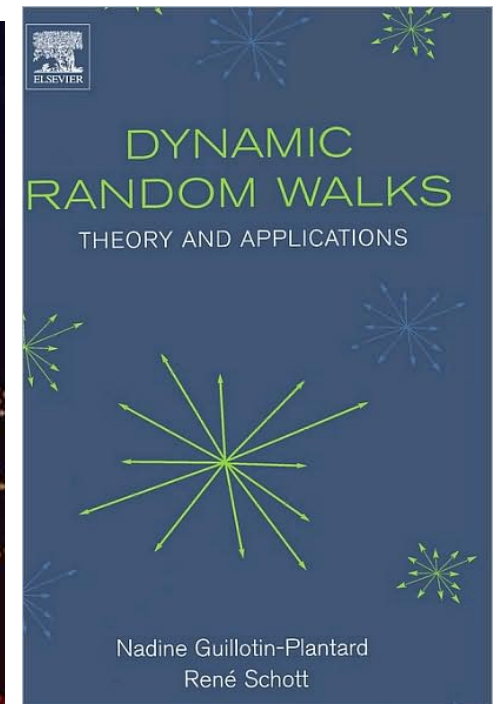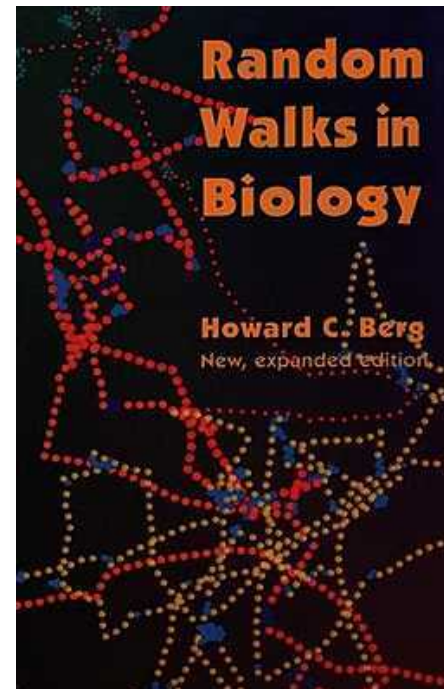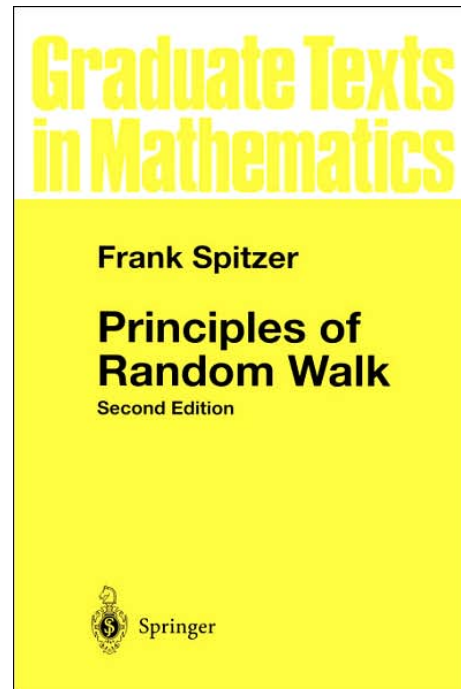
Part 3

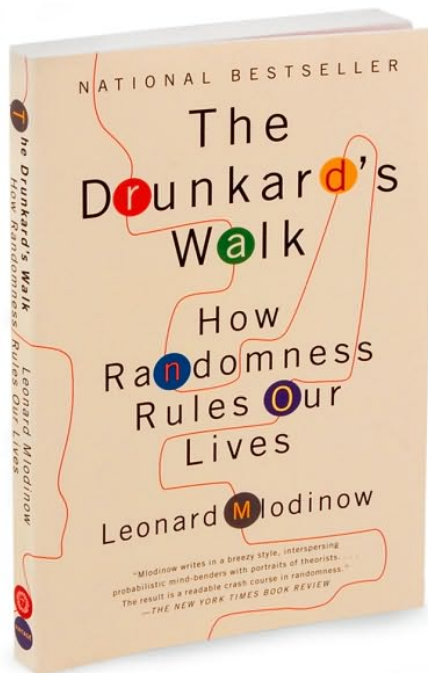## Random Walk

Random Walk

A simple random walk is a sequence of unit steps where each step is taken in the direction of one of the coordinate axis, and each possible direction has equal probability of being chosen.
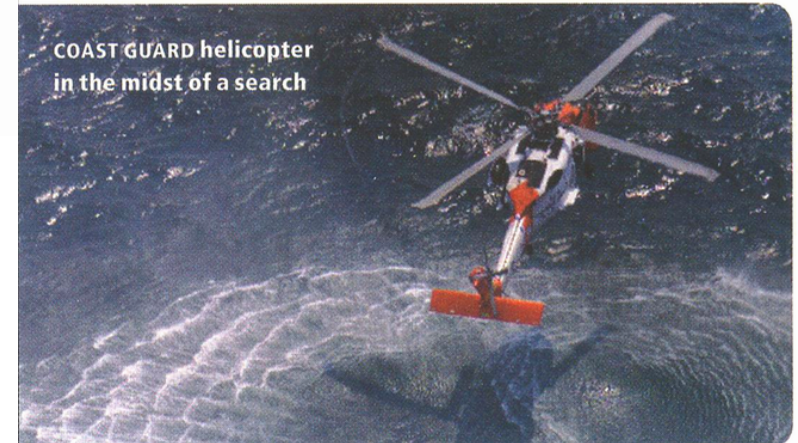
Random walk on a lattice:

- In two dimensions, a single step starting at the point with integer coordinates (x,y) would be equally likely to move to any of one of the four neighbors (x+1,y), (x-1,y), (x,y+1) and (x,y-1).

- In one dimension walk there are two possible neighbors

- In three dimensions there are six possible neighbors.

Random Walk simulates:

- Brownian motion
  (answer the question - how many collisions, on average, a particle must take to travel a distance R).
- Electron transport in metals, …
- …

How does the Coast Guard find people lost at sea?
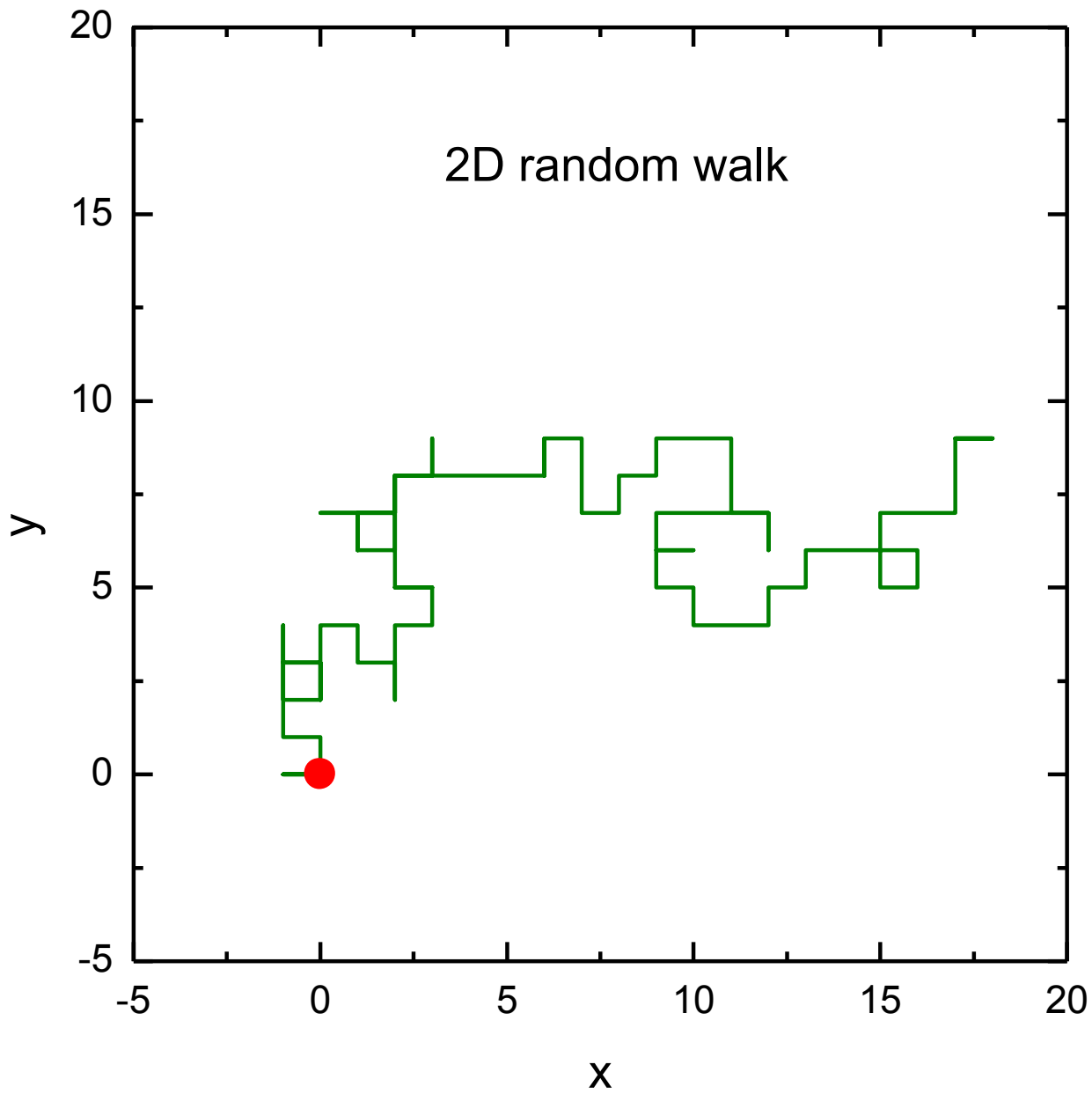
COAST GUARD helicopter in the midst of a search

Then, based on that information, we build a strategy with the help of search-planning software called the Search and Rescue Optimal Planning System (SAROPS), which simulates the trajectory of various kinds of objects as they drift. SAROPS is a Monte Carlo–based system that simulates units called particles. Some particles will represent people in the water; others, the boat. They can all start drifting at different times and locales. With SAROPS, we can make more than 10,000 guesses about where boaters got in trouble and when and where they might end up. The program then assesses which scenario is most probable.
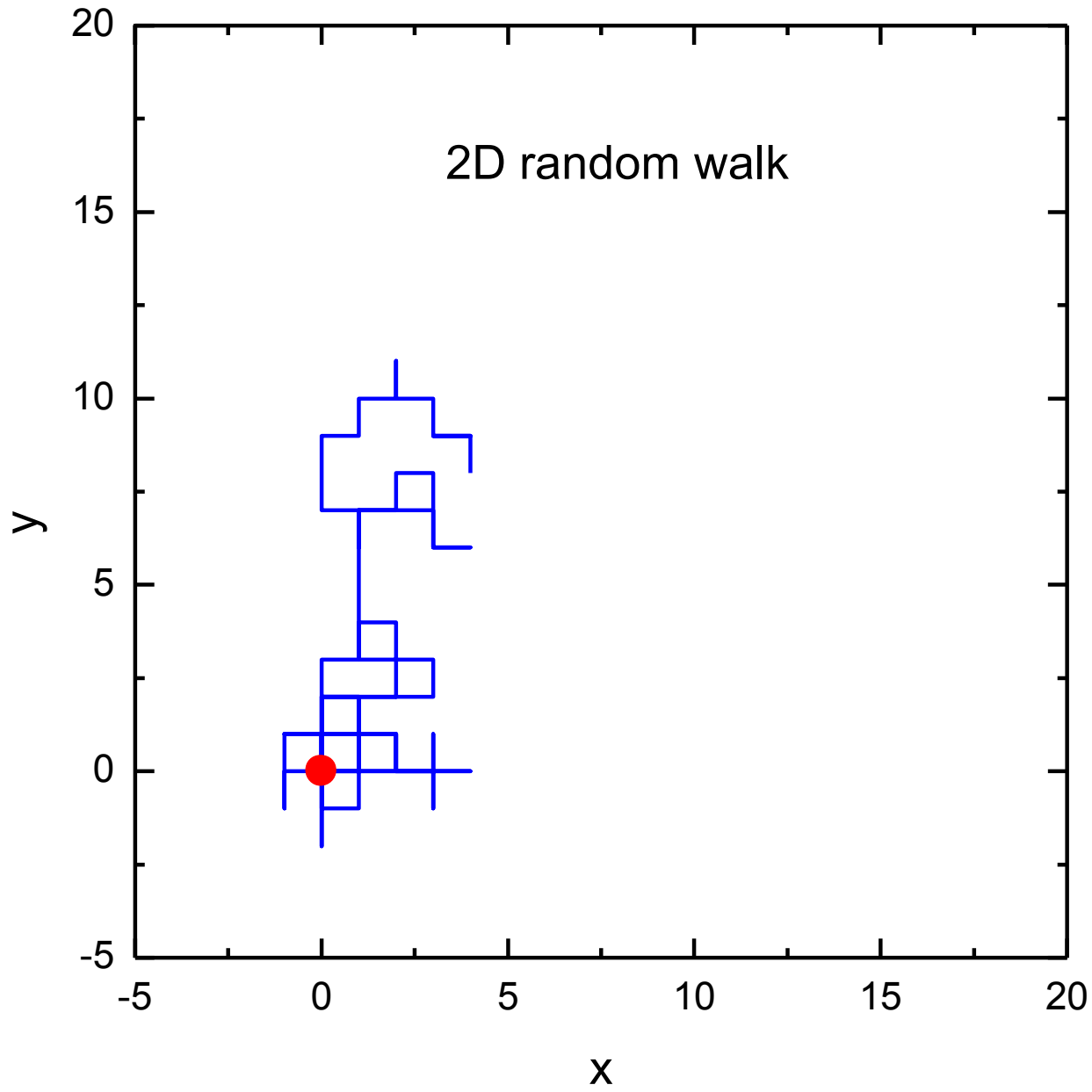
Practice 2 (random walk)

1. Write a program that simulate a random 2D walk with the same step size . Four directions are possible (N, E, S, W).
   Your program will involve two large integers, M = the number of random walks to be taken and N = the maximum number of steps in a single walk.

2. Find the average distance to be from the origin point after N steps

3. Is there any finite bound on the expected number of steps before the first return to the origin?

2D random walk

example

64

example

2D random walk

65

Various models of random walk

Persistent random walk

Restricted random walk

Self-avoiding random walk

…

Examples of applications:

- Spread of inflectional diseases and effects of immunization
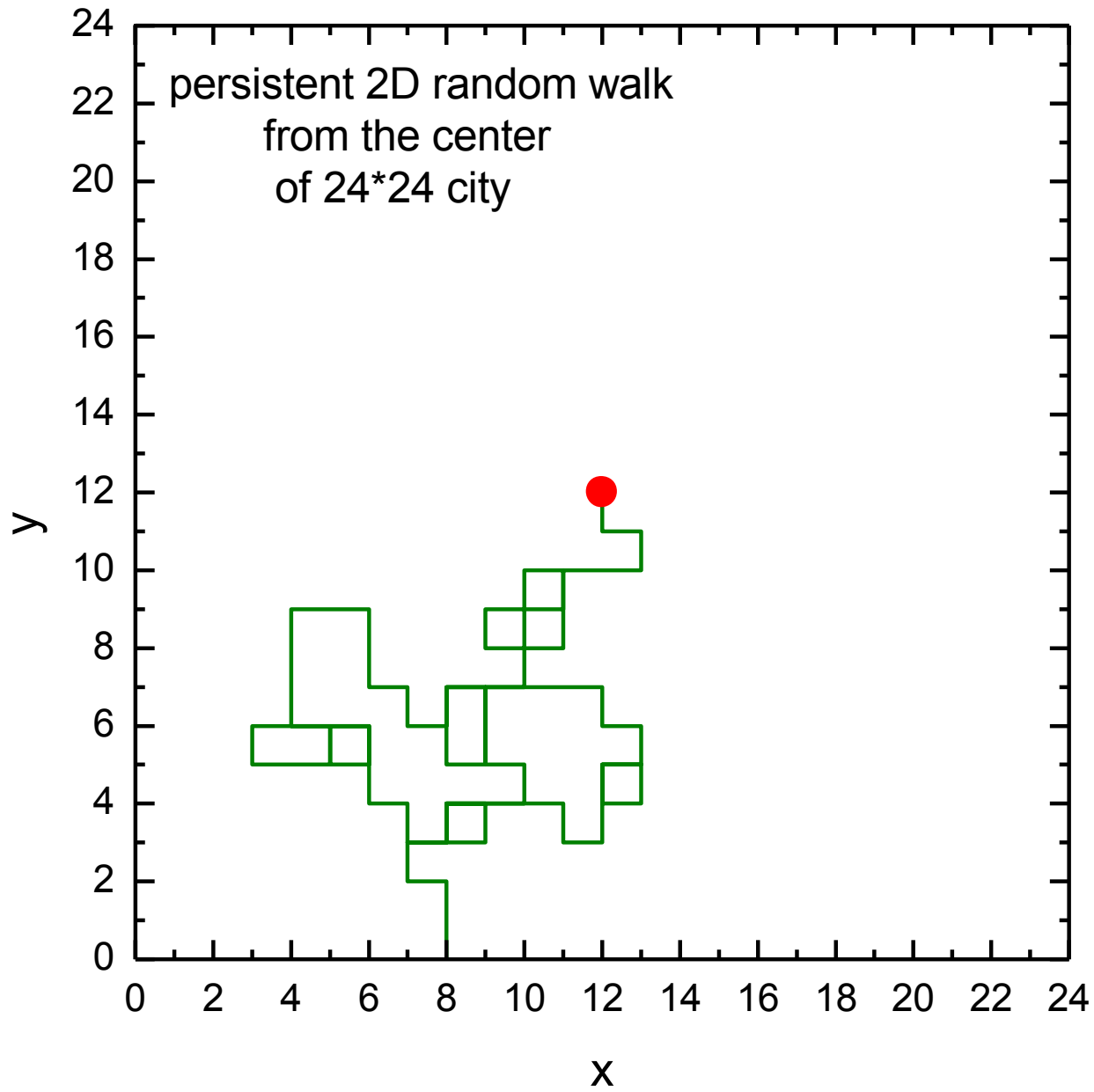- Spreading of fire

A persistent random walk

A persistent random walk in 2 dimensions in a city with n*n blocks
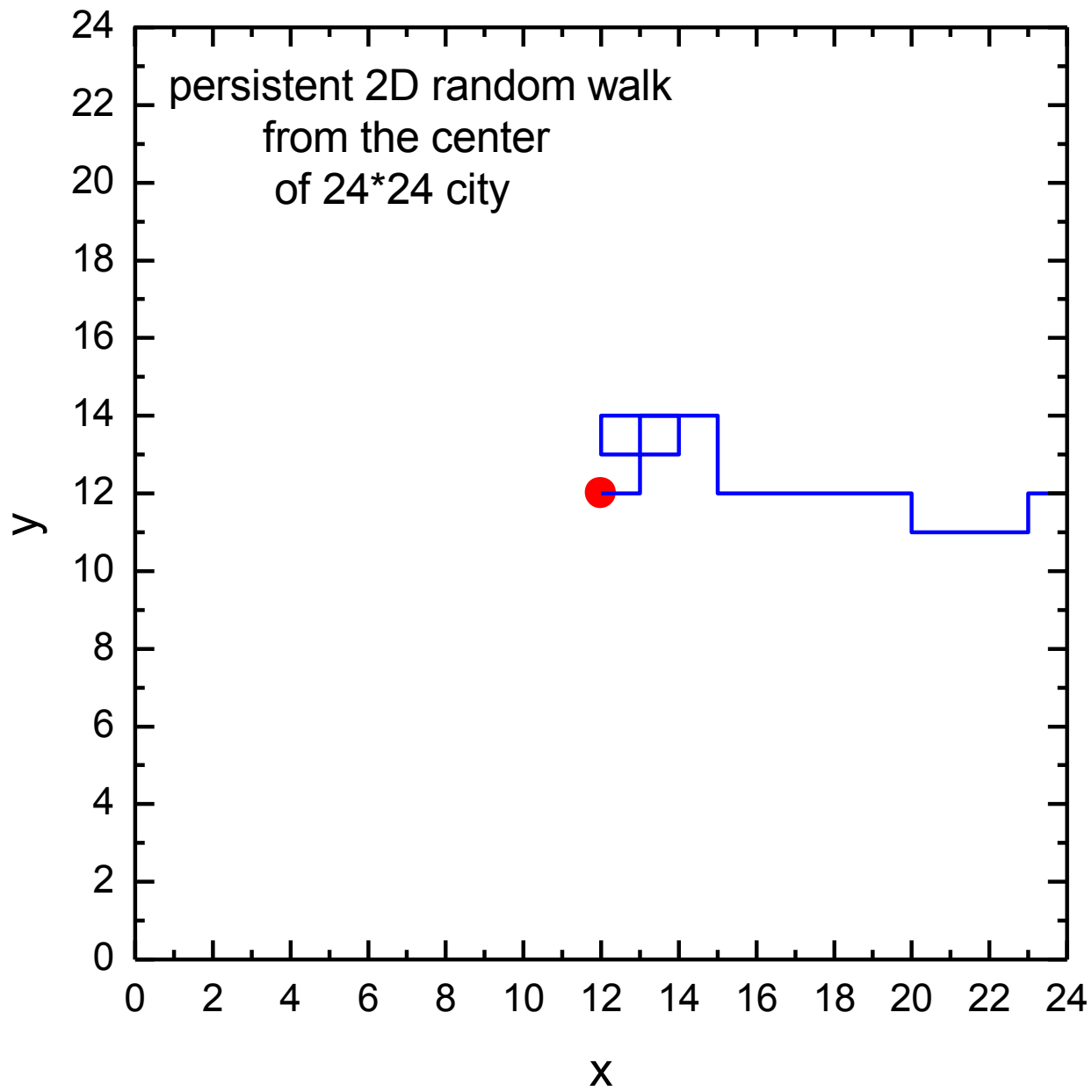
Condition: the walker can not step back
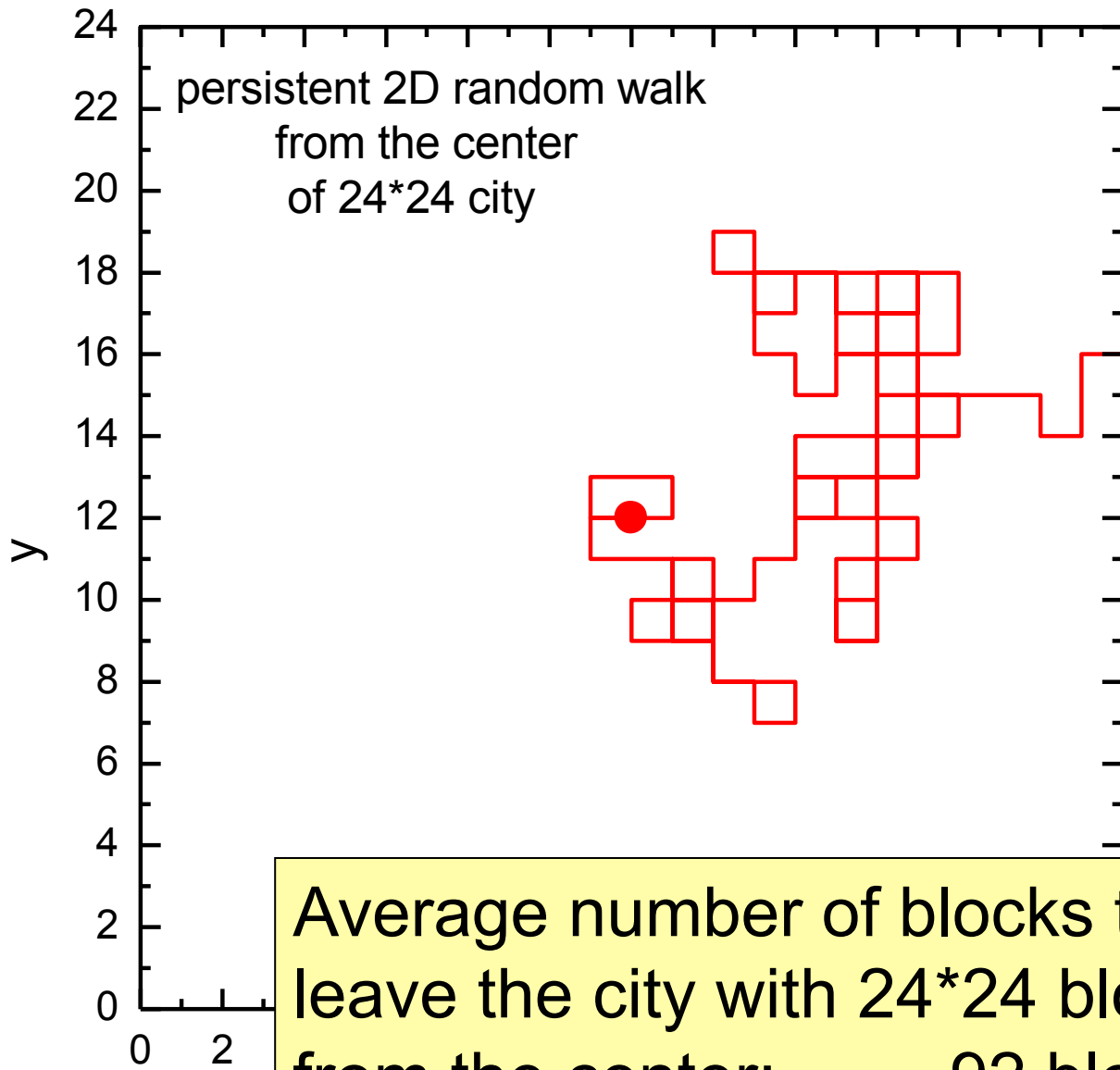
Goal: find average number of steps to get out the city

persistent random walk in a city

persistent 2D random walk
from the center
of 24*24 city

persistent random walk in a city

persistent 2D random walk
from the center
of 24*24 city

persistent random walk in a city

persistent 2D random walk
from the center
of 24*24 city

Average number of blocks to go to
leave the city with 24*24 blocks
from the center: 92 blocks
from a random point: 47 blocks

The Metropolis algorithm (cont.)

The metropolis sampling is most efficient for multidirectional problems.

In a traditional random walk all visiting points are equal. What is we want the random walker to spend more time in a specific region, e.g. where for a 2D walk g(x,y) is larger.

$$x' = x + h(2u_i - 1)$$
$$y' = y + h(2u_{i+1} - 1)$$

then consider

$$q = \frac{g(x', y')}{g(x, y)}$$ and generate

some random number α

if $q \geq \alpha$ the step is accepted

if $q < \alpha$ the step is rejected

Example

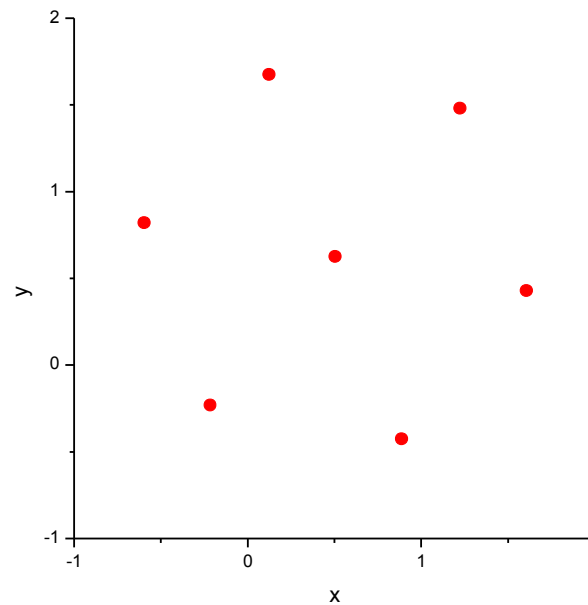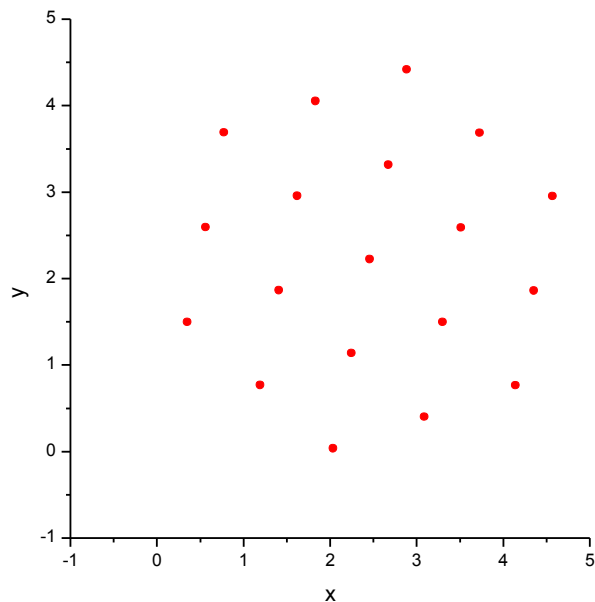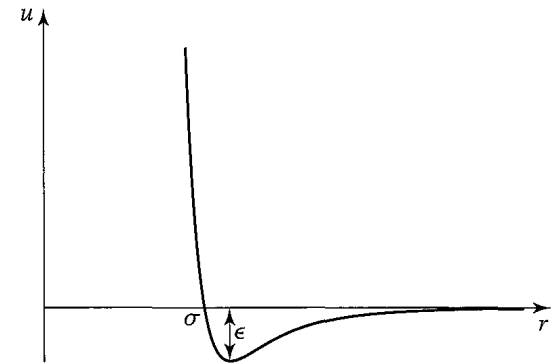a group of atoms interact by Lennard-Jones
potential

$$V(r) = 4\varepsilon\left[\left(\frac{\sigma}{r}\right)^{12} - \left(\frac{\sigma}{r}\right)^{6}\right]$$

Find positions of n atoms that gives the min value of the total potential.
Method: Monte-Carlo variations

examples: n=19   n=7

Example

The French naturalist and mathematician Comte de Buffon showed that the probability that a needle of length L thrown randomly onto a grid of parallel lines with distance D≥L apart intersects a line is 2L/(D*π).

```
c*** loop over trials
      hit = 0
      do it=1,itests
        x0 = float(N)*D*rand()
        k = int(x0/D)
        x1 = x0 - D*float(k)
        x2 = D - x1
        x = min(x1,x2)
        dx = 0.5*abs(L*cos(1.0*pi*rand()))
        if(dx.ge.x) hit = hit + 1
      end do
c*** average number of hits
      ahit = float(hit)/float(itests)
      buffon = (2*L)/(pi*D)
```

```
Buffon problem for D=1
enter numbers of tests
10000
enter numbers of intervals in the grid
10
enter the needle size L<1
0.5
hit    =    3.157E-01
buffon =    3.183E-01
```

```
Buffon problem for D=1
enter numbers of tests
100000
enter numbers of intervals in the grid
50
enter the needle size L<1
0.9
hit    =    5.717E-01
buffon =    5.730E-01
```

Example

investigate a simple problem that generated much attention several years ago and for which many mathematicians obtained an incorrect solution. The problem was the analysis of the optimal strategy in a television game show popular at the time. The show was Let's Make a Deal with host Monty Hall. At some point in the show, a contestant was given a choice of selecting one of three possible items, each concealed behind one of three closed doors. The items varied considerably in value. After the contestant made a choice but before the chosen door was opened, the host, who knew where the most valuable item was, would open one of the doors not selected and reveal a worthless item. The host would then offer to let the contestant select a different door from what was originally selected. The question, of course, is should the contestant switch? A popular magazine writer Marilyn vos Savant concluded that the optimal strategy is to switch. This strategy is counterintuitive to many mathematicians, who would say that there is nothing to be gained by switching; that is, that the probability of improving the selection is 0.5. Study this problem by Monte Carlo methods. What is the probability of improving the selection by switching? Be careful to understand all of the assumptions, and then work the problem analytically also. (A Monte Carlo study is no substitute for analytic study.)

```fortran
c*** loop over trials
      win1 = 0
      win2 = 0
      do it=1,itests
        a(1) = rand()
        a(2) = rand()
        a(3) = rand()
        choice = 1 + int(3.0*rand())
        b(1) = a(choice)
        if(choice.eq.1) b(2) = max(a(2),a(3))
        if(choice.eq.2) b(2) = max(a(1),a(3))
        if(choice.eq.3) b(2) = max(a(1),a(2))
        if(b(1).ge.b(2)) then
           win1 = win1 + 1
           else
           win2 = win2 + 1
        end if
      end do
c*** average number of games and wins
      awin1 = float(win1)/float(itests)
      awin2 = float(win2)/float(itests)
      write (*,101) awin1, awin2
```

Lets make a deal
 enter numbers of tests
10000
 win1 =   3.359E-01
 win2 =   6.641E-01

Example

The gambler's ruin problem. Suppose that a person decides to try to increase the amount of money in his/her pocket by participating in some gambling. Initially, the gambler begin with $m in capital. The gambler decides that he/she will gamble until a certain goal, $n (n>m), is achieved or there is no money left (credit is not allowed). On each throw of a coin (roll of the dice, etc.) the gambler either win $1 or lose $1. If the gambler achieves the goal he/she will stop playing. If the gambler ends up with no money he/she is ruined.

What are chances for the gambler to achieve the goal as a function of k, where k=n/m?

How long on average will it take to play to achieve the goal or to be ruined?

```fortran
      write (*,*)'enter numbers of tests, money and
     goal'
      read  (*,*) itests, money1, money2

c*** loop over trials
      total = 0
      wins = 0
      do it=1,itests
        x=money1
        games=0
        do while(x.gt.0.and.x.lt.money2)
            games = games + 1
            luck = 1
            if(rand().le.0.5) luck=-1
            x = x+luck
        end do
        total = total+games
        if(x.gt.0) wins = wins+1
      end do
c*** average number of games and wins
      agames = float(total)/float(itests)
      awins = float(wins)/float(itests)
      aloose = 1.0-awins
      write (*,100) itests, money1, money2
      write (*,101) awins, aloose, agames
```

```
 The gambler`s ruin problem.
 Chances to reach certain goal
 enter numbers of tests, money and goal
10000
10
100

 tests:      10000
 initial:       10
 goal:         100
 win    =   1.026E-01
 loose  =   8.974E-01
 games  =   9.019E+02
```

chance to win in each bet 50/50

```
 The gambler`s ruin problem.
 Chances to reach certain goal
 enter numbers of tests, money and goal
100000
10
100

 tests:     100000
 initial:       10
 goal:         100
 win    = 9.44000E-03
 loose  = 9.90560E-01
 games  = 4.51806E+02
```

chance to win in each bet 49/51

Applications of Monte-Carlo simulations

- ✓ integration
- ✓ statistical physics
- ✓ aerodynamic
- ✓ quantum chromodynamics
- ✓ molecular dynamic simulation
- ✓ experimental particle physics
- ✓ cellular automata
- ✓ percolation
- ✓ radiation field and energy transport
- ✓ …
- ✓ Finance and business
- ✓ …

Good reference place for Quantum Monte Carlo

http://www.qmcwiki.org/index.php/Research_resources

Cellular automation

Cellular automata – dynamic computational models that are discrete in space, state and time.

Applications – physics, biology, economics, …

Random walk is an example of cellular automata.

see also "The Game of Life" is a cellular automaton devised by John Horton Conway in 1970. Life is an example of emergence and self-organization - complex patterns can emerge from the implementation of very simple rules.