

## HW1 solutions

### Problem 1

$$\begin{aligned}\vec{\nabla} \times \vec{v}^a &= \hat{e}_i \epsilon_{ijk} \frac{\partial}{\partial x_j} \vec{v}_k^a = -6xz\hat{e}_1 + 2z\hat{e}_2 + 3z^2\hat{e}_3 \\ \vec{\nabla} \times \vec{v}^b &= \hat{e}_i \epsilon_{ijk} \frac{\partial}{\partial x_j} \vec{v}_k^b = -2y\hat{e}_1 - 3z\hat{e}_2 - x\hat{e}_3\end{aligned}$$

### Problem 2.

$$T = x^2 + 4xy + 2yz^3$$

$$T(1, 1, 1) - T(0, 0, 0) = 7, \quad \vec{\nabla}T = (2x + 4y)\hat{e}_1 + (4x + 2z^3)\hat{e}_2 + 6yz^2\hat{e}_3$$

(a)

$$\begin{aligned}&\int_0^1 dz (\nabla T)_3 \Big|_{x=y=0} + \int_0^1 dy (\nabla T)_2 \Big|_{x=0, z=1} + \int_0^1 dx (\nabla T)_1 \Big|_{y=z=1} \\ &= 2 \int_0^1 dy + \int_0^1 dx (2x + 4) = 2 + 5 = 7\end{aligned}$$

(b) To calculate a line integral  $\int_{\vec{a}}^{\vec{b}} \vec{dl} \cdot \vec{v}$  we take a parametrization  $x = x(t)$ ,  $y = y(t)$ ,  $z = z(t)$  so that

$$\vec{dl} = \frac{dx(t)}{dt} \hat{e}_1 + \frac{dy(t)}{dt} \hat{e}_2 + \frac{dz(t)}{dt} \hat{e}_3$$

and calculate

$$\int_{\vec{a}}^{\vec{b}} \vec{dl} \cdot \vec{v} = \int_{t_a}^{t_b} dt \left( \frac{dx(t)}{dt} \hat{e}_1 + \frac{dy(t)}{dt} \hat{e}_2 + \frac{dz(t)}{dt} \hat{e}_3 \right) \cdot \vec{v}(x(t), y(t), z(t))$$

In our case it is convenient to take  $t = x$  so  $x = y = t$ ,  $z = t^2$  and therefore

$$\begin{aligned}\int_{(0,0,0)}^{(1,1,1)} \vec{dl} \cdot \vec{\nabla}T &= \int_0^1 dt \left( \hat{e}_1 + \hat{e}_2 + 2t\hat{e}_3 \right) \cdot (6t\hat{e}_1 + (4t + 2t^6)\hat{e}_2 + 6t^5\hat{e}_3) \\ &= \int_0^1 dt [6t + (4t + 2t^6) + 12t^6] = \int_0^1 dt [10t + 14t^6] = 7\end{aligned}$$

Problem 3.

$$\vec{v} = xy\hat{e}_1 + 2yz\hat{e}_2 + 3xz\hat{e}_3, \quad \vec{\nabla} \times \vec{v} = -2y\hat{e}_1 - 3z\hat{e}_2 - x\hat{e}_3$$

The l.h.s. of Stokes theorem is

$$\int_S dydz \hat{e}_1 \cdot \vec{\nabla} \times \vec{v} = \int_0^2 dy \int_0^{2-y} dz (-2y) = - \int_0^2 dy 2y(2-y) = -\frac{8}{3}$$

The r.h.s is a sum of three integrals (for the second integral take the parametrization  $t = z$ )

$$\begin{aligned} \int_{\partial S} \vec{dl} \cdot \vec{v} &= \int_0^2 dy v_2(0, y, 0) + \int_0^2 dt \left( \frac{dx(t)}{dt} \hat{e}_1 + \frac{dy(t)}{dt} \hat{e}_2 + \frac{dz(t)}{dt} \hat{e}_3 \right) \cdot \vec{v}(x(t), y(t), z(t)) \\ &+ \int_2^0 dz v_3(0, 0, z) = \int_0^2 dt \left( -\hat{e}_2 + \hat{e}_3 \right) \cdot \vec{v}(0, 2-t, t) = -2 \int_0^2 dt (2-t)t = -\frac{8}{3} \end{aligned}$$